

KICHIK PARAMETRGA EGA BO'LGAN CHIZIQLI BO'L MAGAN TENGLAMALAR SISTEMASINING DAVRIY YECHIMLARI HAQIDA

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Annotatsiya:

Quyidagi ko'rinishga ega bo'lgan chiziqli bo'l magan ayirmali tenglamalar sistemasini qaraymiz.

$$\begin{aligned} x(t+1) &= Ax(t) + F(t, x(t), y(t), \varepsilon), \\ y(t+1) &= By(t) + \Phi(t, x(t), y(t), \varepsilon), \end{aligned} \quad (1)$$

Kalit so'zlar: tenglamalar sistemasi, cheksiz, ayirmali tenglamalar , qanoatlantiruvchi , vektorlar.

Bunda A, B - haqiqiy o'zgarmaslarga ega bo'lgan $p \times p$ va $q \times q$ - matritsiyalar $F(t, x, y, \varepsilon)$, $\Phi(t, x, y, \varepsilon)$ – p va q o'lchovlarga ega $t \in R = (-\infty; +\infty)$ ε - musbat kichik parametrga ega va t bo'yicha T - davrli uzluksiz vektorlar.

$\varepsilon \rightarrow 0$ da (2.2.1) sistemaning T – davrli $x(t, \varepsilon), y(t, \varepsilon)$ uzluksiz bo'lgan yechim haqidagi savolga javob beramiz.

Faraz qilaylik $A = \text{diag}(A_1, \dots, A_s)$, $B = \text{diag}(B_1, \dots, B_s)$ bunda A_i, B_j – $p_i \times p_j$ va $q_i \times q_j$ – matritsalar

Bunda

$$\sum_{i=1}^r p_i = p, \quad \sum_{j=1}^s q_j = q, \text{ va } \mu \text{ - cheksiz kichik musbat sondir}$$

Quyidagi shartlar bajarilsin

- 1) $|a_i| < 1 < |b_j|$, $i = 1, \dots, s$, $j = 1, \dots, s$;
- 2) $F(t, x, y, \varepsilon)$, $\Phi(t, x, y, \varepsilon)$ vektor funksiyalar $t \in R$, $x \in R^p$, $0 \leq \varepsilon \leq \varepsilon_0$, $y \in R^q$ da uzluksiz, $T - t$ da davriy va Lipshits shartini qanoatlantiradi.

$$|F(t, x', y', \varepsilon') - F(t, x'', y'', \varepsilon'')| \leq l(|x' - x''| + |y' - y''| + |\varepsilon' - \varepsilon''|), \quad (2)$$

$|\Phi(t, x', y', \varepsilon') - \Phi(t, x'', y'', \varepsilon'')| \leq l(|x' - x''| + |y' - y''| + |\varepsilon' - \varepsilon''|)$
bunda $t \in R$, $x', x'' \in R^p$, $y', y'' \in R^q$, $\varepsilon', \varepsilon'' \in [0, \varepsilon_0]$, l – cheksiz kichik miqdor va

$$|x| = \max_{1 \leq i \leq p} |x_i|, \quad |y| = \max_{1 \leq j \leq q} |y_j|,$$

Boshida berilgan ayirmali tenglamalar sistemasini qaraymiz

Bu sistema $\varepsilon = 0$ bo'lganda (2.2.1) dan kelib chiqadi. Kiritilgan xulosalarga ko'ra (2.2.3) sistema uchun (2.1.1) teorema o'rinnlidir, yani yetarlicha kichik μ va l uchun T-davrli ($v(t)$, $w(t)$) uzluksiz bo'lgan yagona yechim mavjuddir Endi (2.2.1) da

$$x(t) = \ddot{x}(t) + v(t), \quad y(t) = \ddot{y}(t) + w(t), \quad (3)$$

Almashtirish bajarsak

$$\check{F}(t, \ddot{x}(t), \ddot{y}(t), \varepsilon) = F(t, \ddot{x}(t) + v(t), \ddot{y}(t) + w(t), \varepsilon) - F(t, v(t), w(t), 0),$$

$$\check{\Phi}(t, \ddot{x}(t), \ddot{y}(t), \varepsilon) = \Phi(t, \ddot{x}(t) + v(t), \ddot{y}(t) + w(t), \varepsilon) - \Phi(t, v(t), w(t), 0).$$

Osonlikda tekshirish mumkinki $F(t, \ddot{x}, \ddot{y}, \varepsilon)$ va $\check{\Phi}(t, \ddot{x}, \ddot{y}, \varepsilon)$ vektor-funksiyalar (2) ni qanoatlantiruvchi bo'lib va $t \in R$ lar uchun quyidagi tengsizliklar o'rinnlidir

$$|\check{F}(t, 0, 0, \varepsilon)| \leq l\varepsilon, \quad |\check{\Phi}(t, 0, 0, \varepsilon)| \leq l\varepsilon \quad (6)$$

Shunday qilib (3) almashtirish yordamida T-davrli (1) sistemaning yechimi mavjudligi shunga o'xshash bo'lgan masala yechimga kelar ekan, bunda $F(t, \ddot{x}, \ddot{y}, \varepsilon)$ $\check{\Phi}(t, \ddot{x}, \ddot{y}, \varepsilon)$ vektor – funksiyalar (2) va (6) shartlarni qanoatlantirishi kerak.

Teorema 1.

1), 2) shartlar bajarilsin. Bu holda

$$\lim_{\varepsilon \rightarrow 0} |\check{v}(t, \varepsilon)| = 0, \quad (7)$$

$$\lim_{\varepsilon \rightarrow 0} |\check{w}(t, \varepsilon)| = 0,$$

(2.2.5) da

$$\ddot{x}(t) = \ddot{\ddot{x}}(t) + \check{v}(t, \varepsilon), \quad \ddot{y}(t) = \ddot{\ddot{y}}(t) + \check{w}(t, \varepsilon),$$

almashtirish bajarsak quyidagi tenglamalar sistemasini hosil qilamiz.

$$\ddot{\ddot{x}}(t+1) = A\ddot{\ddot{x}}(t) + \check{F}(t, \ddot{x}(t) + \check{v}(t, \varepsilon), \ddot{y}(t) + \check{w}(t, \varepsilon), \varepsilon) - \check{F}(t, \check{v}(t, \varepsilon), \check{w}(t, \varepsilon), \varepsilon) \quad (2.2.12)$$

$$\ddot{\ddot{y}}(t+1) = B\ddot{\ddot{y}}(t) + \check{\Phi}(t, \ddot{x}(t) + \check{v}(t, \varepsilon), \ddot{y}(t) + \check{w}(t, \varepsilon), \varepsilon) - \check{\Phi}(t, \check{v}(t, \varepsilon), \check{w}(t, \varepsilon), \varepsilon)$$

Adabiyotlar ro'yxati

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